

<b>Title</b>	Asymptotic behavior and area growth of minimal surfaces in $\mathbf{H}^n$
<b>Author</b>	Chen, Qing / Cheng, Yi
<b>Citation</b>	Osaka Journal of Mathematics. 36(2); 397-407
<b>Issue Date</b>	1999-06
<b>ISSN</b>	0030-6126
<b>Textversion</b>	Publisher
<b>Relation</b>	The OJM has been digitized through Project Euclid platform <a href="http://projecteuclid.org/ojm">http://projecteuclid.org/ojm</a> starting from Vol. 1, No. 1.

Placed on: Osaka City University

## ASYMPTOTIC BEHAVIOR AND AREA GROWTH OF MINIMAL SURFACES IN $\mathbf{H}^n$

QING CHEN and YI CHENG

(Received February 19, 1996)

Let  $\mathbf{H}^n$  be the hyperbolic  $n$ -space of constant curvature  $-1$ . We identify  $\mathbf{H}^n$  with the unit ball in the Euclidean  $n$ -space  $\mathbf{R}^n$  via the Poincare model, i.e.,  $\mathbf{H}^n = (B^n(1), \frac{4ds^2}{(1-r^2)^2})$ , where  $ds^2$  is the Euclidean metric and  $r$  is the Euclidean distance from the origin. The sphere  $\partial B^n(1)$  is called the sphere at infinity and denoted by  $S^{n-1}(\infty)$ . It represents the asymptotic classes of geodesics in  $\mathbf{H}^n$ . Let  $M$  be an immersed complete minimal surface in  $\mathbf{H}^n$ . The intersection of the closure of  $M$  in the Euclidean topology with  $S^{n-1}(\infty)$  can be seen as the asymptotic boundary of  $M$ . In [1], M.T. Anderson established the general existence theorem of complete area-minimizing current with prescribed asymptotic boundary, which enclosed the following result as a special case:

*Let  $C$  be a smooth closed curve (or more generally, closed 1-current) in  $S^{n-1}(\infty)$ , then there is a complete area-minimizing smooth surface  $M$  with asymptotic boundary  $C$ .*

This paper is concerned with the asymptotic behaviour of complete minimal surfaces in  $\mathbf{H}^n$ . This is partially suggested by the "good" behaviour at infinity of complete minimal surfaces in  $\mathbf{R}^n$  with finite total Gaussian curvature, namely, the tangent cone at infinity of a such minimal surface is uniquely a collection of 2-plane with multiplicities (see [2],[3],[5]). But the situation is different in  $\mathbf{H}^n$ . One of the differences is the above mentioned result of Anderson; another is that the total Gaussian curvature of complete minimal surface in  $\mathbf{H}^n$  is infinite ( this can be seen by the Gauss equation). We will study a class of minimal surfaces in  $\mathbf{H}^n$  with minimal area growth ( see §1 of the definition ). We present some geometric descriptions of such surfaces, and find that the "length" of their asymptotic boundary in  $S^{n-1}(\infty)$  are finite ( see Theorem 3.2 ). A corollary of our theorems is (Corollary 3.3)

*Let  $M$  be a properly immersed complete and oriented minimal surface in  $\mathbf{H}^n$  with Gaussian curvature  $K$ . Suppose  $M$  has finite topological type and*

$$-\int_M (1 + K) < +\infty,$$

then the asymptotic boundary of  $M$  is a rectifiable 1-varifold with finite mass.

This paper is organized as follows. In section 1, we introduce some basic properties of minimal surfaces in  $\mathbf{H}^n$ . In section 2 we present Theorem 2.1 which establishes a relation between the area growth of a minimal surface in  $\mathbf{H}^n$  and some weighted  $L^2$ -norm of its second fundamental form. The corresponding result of minimal surfaces in  $\mathbf{R}^n$  was obtained in a previous paper [2]. In section 3, we discuss the Euclidean area and boundary structure of a minimal surface in  $\mathbf{H}^n$ . Since the asymptotic boundary of a minimal surface in  $\mathbf{H}^n$  is not a smooth curve in general, some concepts from geometric measure theory should be employed in the proof of the theorem. We refer to [8] for a reference of definitions and terminology of geometric measure theory.

Part of this work was finished by the first author in the Graduate School of Mathematical Science, The University of Tokyo. He would like to thank Professor OCHIAI Takoshiro and Professor KASUE Atsushi for their sincere guidance. The authors would like to thank the referee for many useful comments.

## 1. Preliminaries

Throughout this paper  $\mathbf{H}^n$  denotes the hyperbolic  $n$ -space of constant curvature  $-1$ , and  $M$  an oriented and properly immersed complete minimal surface in  $\mathbf{H}^n$ . We first recall some well-known facts.

**Proposition 1.1.** (*Monotonicity formula, Theorem 1 of [1]*) *Let  $B(t)$  be the geodesic ball of  $\mathbf{H}^n$  centered at a fixed point and radius  $t$ , and set  $M(t) = M \cap B(t)$  and  $v(t) = \text{Area}M(t)$ . Then the function*

$$\frac{v(t)}{\cosh t - 1}$$

is monotone non-decreasing in  $t$ , particularly,

$$v'(t) \cosh t - v(t) \sinh t \geq v'(t).$$

**DEFINITION 1.2.**  *$M$  is said to have minimal area growth if*

$$\sup \frac{v(t)}{\cosh t - 1} < +\infty.$$

The following proposition is a direct consequence of the definitions of the Hessian and the second fundamental form, for the proof see [6].

**Proposition 1.3.** *Let  $A$  be the second fundamental form of  $M$ ,  $\rho$  the distance function of  $H^n$  from a fixed point and  $\nabla$  the covariant derivative of  $M$ , then*

$$(\nabla^2 \rho)(e, e) = \coth \rho(1 - \langle e, \nabla \rho \rangle^2) + \langle A(e, e), \nabla^\perp \rho \rangle,$$

for any unit tangent vector  $e$  of  $M$ , where  $\nabla^\perp \rho$  is the normal projection of  $\text{Grad}_{H^n} \rho$  to  $M$ .

The restriction of distance  $\rho$  on  $M$  is smooth. By Sard's theorem, for almost all  $t > 0$ ,  $\overline{M(t)}$  is a compact surface with boundary  $\partial M(t)$  being an immersed closed curve. Denote the geodesic curvature of  $\partial M(t)$  by  $k_g^t$ . Then the Gauss-Bonnet formula is

$$(1.1) \quad \int_{\partial M(t)} k_g^t + \int_{M(t)} K = 2\pi\chi(M(t)),$$

where  $K$  is the Gaussian curvature of  $M$ , and  $\chi(M(t))$  is the Euler characteristic of  $M(t)$ . Substituting the Gauss equation  $K = -1 - \frac{1}{2}|A|^2$  into (1.1), and putting  $R(t) = \int_{M(t)} |A|^2$ , then

$$(1.2) \quad v(t) + \frac{1}{2}R(t) + 2\pi\chi(M(t)) = \int_{\partial M(t)} k_g^t.$$

Suppose  $e$  is tangent to  $\partial M(t)$ . Then,  $\frac{\nabla \rho}{|\nabla \rho|}$  being normal to  $\partial M(t)$  in  $M$ , the expression of  $k_g^t$  is

$$(1.3) \quad \begin{aligned} k_g^t &= -\langle \nabla_e e, \frac{\nabla \rho}{|\nabla \rho|} \rangle \\ &= \frac{1}{|\nabla \rho|} (\nabla^2 \rho)(e, e) \\ &= \frac{1}{|\nabla \rho|} (\coth \rho + \langle A(e, e), \nabla^\perp \rho \rangle), \end{aligned}$$

where the last equality is followed by Proposition 1.2.

By the co-area formula (see [8]),  $v'(t) = \int_{\partial M(t)} \frac{1}{|\nabla \rho|}$ . Substituting (1.3) into (1.2), we obtain

**Proposition 1.4.** *For almost all  $t > 0$ ,*

$$v(t) + \frac{1}{2}R(t) + 2\pi\chi(M(t)) = v'(t) \coth t - \int_{\partial M(t)} \langle A(\frac{\nabla \rho}{|\nabla \rho|}, \frac{\nabla \rho}{|\nabla \rho|}), \frac{\nabla^\perp \rho}{|\nabla \rho|} \rangle.$$

**2. Area growth estimate**

In this section we prove the following theorem, which is analogous to Theorem 1 of [2].

**Theorem 2.1.** *Let  $M$  be a properly immersed complete minimal surface in  $\mathbf{H}^n$ . Suppose  $M$  is of finite topological type. Then  $M$  has minimal area growth if and only if*

$$\int_M e^{-\rho(x)} |A|^2(x) dx < +\infty,$$

where  $A$  is the second fundamental form of  $M$  and  $\rho$  is the distance function of  $\mathbf{H}^n$  to a fixed point.

**Lemma 2.2.** *For  $t > s > t_0 \geq 0$ ,*

$$\begin{aligned} & \frac{\int_{M(t)-M(t_0)} \cosh \rho}{\cosh^2 t} - \frac{\int_{M(s)-M(t_0)} \cosh \rho}{\cosh^2 s} = \\ & \int_{M(t)-M(s)} \frac{1 + |\nabla^\perp \rho|^2 \sinh^2 \rho}{\cosh^3 \rho} + \int_s^t \frac{\sinh t_0 \sinh u}{\cosh^3 u} \int_{\partial M(t_0)} |\nabla \rho|. \end{aligned}$$

Proof. By the minimality of  $M$  and Proposition 1.3, we observe that

$$\Delta \rho = (2 - |\nabla \rho|^2) \coth \rho,$$

where  $\Delta$  is the Laplacian of  $M$ . It yields

$$(2.1) \quad \Delta \cosh \rho = 2 \cosh \rho.$$

Integrating (2.1) over  $M(t) - M(t_0)$  and by using Green’s formula, we have

$$(2.2) \quad 2 \int_{M(t)-M(t_0)} \cosh \rho = \int_{\partial M(t)} |\nabla \rho| \sinh \rho - \int_{\partial M(t_0)} |\nabla \rho| \sinh \rho.$$

The co-area formula ([8]) leads

$$\begin{aligned} & \frac{d}{dt} \left( \frac{\int_{M(t)-M(t_0)} \cosh \rho}{\cosh^2 t} \right) \\ (2.3) \quad & = \frac{1}{\cosh^3 t} \left( \cosh t \int_{\partial M(t)} \frac{\cosh \rho}{|\nabla \rho|} - 2 \sinh t \int_{M(t)-M(t_0)} \cosh \rho \right) \\ & = \frac{1}{\cosh^3 t} \left( \int_{\partial M(t)} \left( \frac{\cosh^2 t}{|\nabla \rho|} - |\nabla \rho| \sinh^2 t \right) + \sinh t_0 \sinh t \int_{\partial M(t_0)} |\nabla \rho| \right) \\ & = \frac{1}{\cosh^3 t} \left( \int_{\partial M(t)} \frac{1}{|\nabla \rho|} (1 + |\nabla^\perp \rho|^2 \sinh^2 t) + \sinh t_0 \sinh t \int_{\partial M(t_0)} |\nabla \rho| \right). \end{aligned}$$

The lemma is then proved by integrating (2.3) from  $s$  to  $t$  and the co-area formula.

Proof of Theorem 2.1. By the co-area formula,

$$\begin{aligned}
 (2.4) \quad \int_{M(t)} e^{-\rho} |A|^2 &= \int_0^t e^{-s} R'(s) ds \\
 &= e^{-t} R(t) + \int_0^t e^{-s} R(s) ds.
 \end{aligned}$$

We rewrite Proposition 1.4 as

$$\begin{aligned}
 (2.5) \quad \frac{v'(t) \cosh t - v(t) \sinh t}{\sinh t} &= \frac{1}{2} R(t) + 2\pi\chi(M(t)) \\
 &\quad + \int_{\partial M(t)} \left\langle A \left( \frac{\nabla \rho}{|\nabla \rho|}, \frac{\nabla \rho}{|\nabla \rho|}, \frac{\nabla^\perp \rho}{|\nabla \rho|} \right) \right\rangle.
 \end{aligned}$$

From now on,  $C_i (i = 1, 2, \dots)$  will be denoted as constants independent of  $t$ .

If  $\int_M e^{-\rho(x)} |A|^2(x) dx < +\infty$ , by (2.5) we have

$$(2.6) \quad \frac{d}{dt} \frac{v(t)}{\cosh t} \leq \frac{\sinh t}{\cosh^2 t} \left( \frac{1}{2} R(t) + 2\pi\chi(M(t)) \right) + \int_{\partial M(t)} \frac{|A| |\nabla^\perp \rho| \sinh t}{|\nabla \rho| \cosh^2 t}.$$

Integrating (2.6) from 0 to  $t$  and by the co-area formula,

$$(2.7) \quad \frac{v(t)}{\cosh t} \leq 2 \int_0^t \left( \frac{1}{2} R(s) + 2\pi\chi(M(s)) \right) e^{-s} ds + \int_{M(t)} |A| \frac{|\nabla^\perp \rho| \sinh \rho}{\cosh^2 \rho}$$

Since  $\chi(M(t)) \leq 1$ , by using the Schwarz inequality, (2.7) and the hypothesis, we have

$$\begin{aligned}
 (2.8) \quad \frac{v(t)}{\cosh t} &\leq C_1 + \left( \int_{M(t)} \frac{|A|^2}{\cosh \rho} \right)^{\frac{1}{2}} \left( \int_{M(t)} \frac{|\nabla^\perp \rho|^2 \sinh^2 \rho}{\cosh^3 \rho} \right)^{\frac{1}{2}} \\
 &\leq C_1 + C_2 \left( \frac{\int_{M(t)} \cosh \rho}{\cosh^2 t} \right)^{\frac{1}{2}} \quad (\text{by Lemma 2.2}) \\
 &\leq C_1 + C_2 \left( \frac{v(t)}{\cosh t} \right)^{\frac{1}{2}}.
 \end{aligned}$$

Thus by the monotonicity of  $\frac{v(t)}{\cosh t}$  we see either  $\sup \frac{v(t)}{\cosh t} \leq C_1^2$  or, when  $t$  is large enough,  $C_1^2 < \frac{v(t)}{\cosh t}$ , so

$$\frac{v(t)}{\cosh t} \leq \left( \frac{v(t)}{\cosh t} \right)^{\frac{1}{2}} + C_2 \left( \frac{v(t)}{\cosh t} \right)^{\frac{1}{2}}.$$

It follows

$$\sup \frac{v(t)}{\cosh t} \leq \max\{C_1^2, (1 + C_2)^2\},$$

this proves that  $M$  has minimal area growth.

Conversely, when  $\sup \frac{v(t)}{\cosh t} < \infty$ , it suffices to show  $\int_0^\infty e^{-t}R(t)dt < +\infty$ . Indeed, this implies that there is a sequence  $\{t_i\}$  tending to infinity such that  $e^{-t_i}R(t_i) \rightarrow 0$  as  $i \rightarrow \infty$ , taking  $t = t_i$  in (2.4) then letting  $i$  tending to infinity, the theorem follows.

we derive from (2.5) that

$$(2.9) \quad \frac{1}{2}R(t)e^{-t} \leq -2\pi\chi(M)e^{-t} + \frac{e^{-t} \cosh^2 t}{\sinh t} \frac{d}{dt} \left( \frac{v(t)}{\cosh t} \right) + \int_{\partial M(t)} \frac{e^{-t}|A||\nabla^\perp \rho|}{|\nabla \rho|},$$

and we integrate above inequality from 0 to  $t$ . Then, since the integrals of the first two terms in the right hand side of (2.9) is bounded above, we have

$$(2.10) \quad \begin{aligned} \frac{1}{2} \int_0^t e^{-s}R(s)ds &\leq C_3 + \int_{M(t)} e^{-\rho}|A||\nabla^\perp \rho| \\ &\leq C_3 + \sqrt{\int_{M(t)} e^{-\rho}|A|^2 \int_{M(t)} e^{-\rho}|\nabla^\perp \rho|^2} \\ &\leq C_3 + C_4 \sqrt{\int_{M(t)} e^{-\rho}|A|^2}, \end{aligned}$$

where the last inequality is followed by Lemma 2.2. For the convenience we set

$$f(t) = \int_0^t e^{-s}R(s)ds.$$

Combining (2.10) with (2.4) we obtain

$$(2.11) \quad \frac{1}{2}f(t) \leq C_3 + C_4\sqrt{f(t) + f'(t)}.$$

We claim that either of the following holds:

(a):  $\int_0^\infty e^{-t}R(t)dt = \sup f(t) \leq 2C_3$ ,

(b): there is a sequence  $\{t_i\}$  tending to infinity such that  $f'(t_i) < f(t_i)$ ,

otherwise, there is a  $t_0$  sufficient large such that  $f(t) < f'(t)$  and  $f(t) > 2C_3$  when  $t \geq t_0$ , then by (2.11)

$$\frac{8C_4^2 f'(t)}{(f(t) - 2C_3)^2} \geq 1,$$

integrating this from  $t_0$  to  $t$ , we get

$$8C_4^2 \left( \frac{1}{f(t_0) - 2C_3} - \frac{1}{f(t) - 2C_3} \right) \geq t - t_0,$$

which contradicts with the fact that  $t$  is unbounded.

It remains to prove the theorem when (b) holds. Taking  $t = t_i$  in (2.11), one has

$$(2.12) \quad \frac{1}{2}f(t_i) \leq C_3 + C_4\sqrt{2f(t_i)}.$$

If  $f(t_i) \rightarrow \infty$  as  $i \rightarrow \infty$ , then dividing (2.12) by  $f(t_i)$  and letting  $i \rightarrow \infty$  would lead to an obvious contradiction. Hence  $\sup f(t) = \sup f(t_i) < \infty$  and the theorem follows.

### 3. Boundary behaviour of minimal surfaces

We regard  $\mathbf{H}^n$  as the Poincaré model, that is  $\mathbf{H}^n = (B^n(1), ds_H^2)$ , where  $B^n(1)$  is the unit ball of  $\mathbf{R}^n$  and  $ds_H^2 = \frac{4}{(1-r^2)^2}ds_E^2$  with  $r$  being the Euclidean distance function from the origin. Here and after, the subscripts  $H$  and  $E$  indicate, respectively, the notations with respect to the hyperbolic metric and the Euclidean metric.

**Theorem 3.1.** *Suppose  $M \mapsto (B^n(1), ds_H)$  is a properly immersed complete minimal surface. If  $\sup \frac{v_H(t)}{\cosh t} < \infty$  then  $\text{Area}_E(M) < \infty$ .*

Proof. For  $p \in M$ , the orthonormal basis  $e_1, e_2$  (or  $\tilde{e}_1, \tilde{e}_2$ ) of  $T_pM$  with respect to the Euclidean metric (or the hyperbolic metric) is related by

$$\tilde{e}_i = \frac{1 - r^2(p)}{2} e_i, \quad i = 1, 2.$$

Since  $r = \tanh \frac{\rho}{2}$ , we have

$$(3.1) \quad \begin{aligned} \nabla_E r(p) &= \sum_{i=1}^2 e_i(r) e_i \\ &= \sum_{i=1}^2 \frac{4}{(1-r^2)^2} \tilde{e}_i(r) \tilde{e}_i \\ &= (1 + \cosh \rho)^2 \sum_{i=1}^2 \tilde{e}_i \left( \tanh \frac{\rho}{2} \right) \tilde{e}_i \\ &= (1 + \cosh \rho) \nabla_H \rho(p). \end{aligned}$$



It follows  $|\nabla_{E^r}|_E = |\nabla_H \rho|_H$ . Then the co-area formula yields

$$\begin{aligned}
 (3.2) \quad v'_H(t) &= \int_{\partial(M \cap B_H(t))} \frac{1}{|\nabla_H \rho|_H} ds_H \\
 &= \int_{\partial(M \cap B_E(\tanh \frac{t}{2}))} \frac{1}{|\nabla_{E^r}|_E} \frac{2}{1 - \tanh^2 \frac{t}{2}} ds_E \\
 &= (\cosh t + 1)v'_E(\tanh \frac{t}{2}),
 \end{aligned}$$

hence, by Proposition 1.1 we have

$$\begin{aligned}
 (3.3) \quad +\infty &> \int_0^\infty \frac{d}{dt} \left( \frac{v_H(t)}{\cosh t} \right) dt \\
 &\geq \int_0^\infty \frac{v'_H(t)}{\cosh^2 t} dt \\
 &= \int_0^\infty \frac{(1 + \cosh t)^2}{\cosh^2 t} v'_E(\tanh \frac{t}{2}) d(\tanh \frac{t}{2}) \\
 &\geq \int_0^\infty v'_E(\tanh \frac{t}{2}) d(\tanh \frac{t}{2}) \\
 &= \text{Area}_E(M).
 \end{aligned}$$

This completes the proof.

Next we discuss the boundary behaviour of minimal surfaces. Following Anderson [1], the asymptotic boundary  $\partial M$  of a complete minimal surface  $M$  in  $\mathbf{H}^n$  is defined by

$$\partial M = \text{closure}(M) \cap S^{n-1}(\infty),$$

where the closure is taken in the Euclidean topology. When  $M$  is properly immersed, then  $\partial M$  is just the boundary of  $M$  in the Euclidean space  $R^n$ .

**Theorem 3.2.** *Let  $M$  be an immersed complete minimal surface in  $\mathbf{H}^n$  with minimal area growth and finite topological type. Then the asymptotic boundary  $\partial M$  of  $M$  is a rectifiable 1-varifold with finite mass when  $\partial M$  is considered as a subset of  $S^{n-1}(\infty) \subset R^n$ .*

*Proof.* We claim that  $M$  is properly immersed, which can be proved in the same way as the proof of Lemma 3 in [2]. Hence the boundary  $\partial M(t)$  of  $M(t) = M \cap B_H(t)$  is a smooth closed curve, for almost all  $t > 0$ . Since

$$\text{length}_E(\partial M(t)) = \int_{\partial M(t)} ds_E = \frac{1}{1 + \cosh t} \text{length}_H(\partial M(t)).$$

By the minimal growth of the area, there is a sequence  $\{t_i\}$  tending to infinity such that

$$\sup \text{length}_E(\partial M(t_i)) = \sup \frac{\text{length}_H(\partial M(t_i))}{\cosh t_i + 1} < \infty.$$

By the compactness theorem of current (Theorem 27.3 of [8]), there is a subsequence of  $\{\partial M(t_i)\}$ , denoted again by  $\{\partial M(t_i)\}$ , converges to an integer multiplicity 1-current as currents in  $\mathbf{R}^n$ . If we regard  $\partial M(t_i)$  as a rectifiable 1-varifold in  $B^n(1) \subset R^n$ , then  $\{\partial M(t_i)\}$  also converges to a rectifiable 1-varifold  $\mathcal{V}$  with integer multiplicity.

Suppose  $\mathcal{V} = \underline{v}(\Sigma, \theta)$ , where  $\Sigma = \text{support}(\mathcal{V})$  and  $\theta$  is the multiplicity function of  $\mathcal{V}$ . It is obvious that  $\Sigma \subset \partial M$ . In the following we show actually  $\mathcal{V} = \underline{v}(\partial M, \theta)$ , then the theorem follows.

Denote  $\mathcal{H}^1$  the 1-dimensional Hausdorff measure of  $\mathbf{R}^n$ , and  $\mu_v$  the weight measure of  $\mathcal{V}$ . By the convergence,

$$\mathcal{H}^1|_{\partial M(t_i)} \rightarrow \mu_v \quad (i \rightarrow \infty)$$

as the Radon measures. Suppose  $p \in \partial M - \Sigma \neq \phi$ , there is a neighbourhood  $O$  of  $p$  in  $\mathbf{R}^n$  such that  $\Sigma \cap O = \phi$ . We can choose  $O$  to be a ball in  $\mathbf{R}^n$  such that  $\partial O \cap B^n(1)$  is a hyperplane of  $H^n$ . Then

$$(3.4) \quad \text{length}_E(O \cap \partial M(t_i)) = \mathcal{H}^1(O \cap \partial M(t_i)) \rightarrow \mu_v(B_E(p, \epsilon)) = 0.$$

Since  $M$  has finite topological type,  $p$  represents an end  $V$  of  $M$ , which is topologically an annulus. Let  $C_i = V \cap O \cap \partial M(t_i)$ . If  $C_i$  is not a closed curve, taking  $p_i \in C_i$  such that  $p_i \rightarrow p$ , then

$$\text{length}_E(C_i) \geq \text{dist}_E(p_i, \partial O) \geq \text{dist}_E(p, \partial O) - \text{dist}_E(p_i, p).$$

This implies by (3.4) that  $C_i$  is a closed curve when  $i$  is sufficiently large. By the convex hull property of minimal surface in  $H^n$  (Lemma 5 of [1]), when  $i \geq i_0$ ,

$$V(t_i) := V \cap (M(t_i) - M(t_{i_0})) \subset O.$$

Applying Lemma 2.2 to  $V(t_i)$ ,

$$\int_{V(t_i)} \cosh \rho ds_H^2 \geq \cosh^2 t_i \int_{V(t_i)} \frac{1 + |\nabla^\perp \rho|^2 \sinh^2 \rho}{\cosh^3 \rho} ds_H^2.$$

Now (2.2) implies

$$\begin{aligned} \mathcal{H}^1(C_i) &= \frac{\text{length}_H(C_i)}{1 + \cosh t_i} \\ &\geq \frac{1}{\sinh t_i (1 + \cosh t_i)} \int_{V(t_i)} \cosh \rho ds_H^2 \\ &\geq \frac{\cosh^2 t_i}{\sinh t_i (1 + \cosh t_i)} \int_{V(t_i)} \frac{1 + |\nabla^\perp \rho|^2 \sinh^2 \rho}{\cosh^3 \rho} ds_H^2, \end{aligned}$$

which contradicts (3.4). This completes the proof of the theorem.

**Corollary 3.3.** *Let  $M$  be a properly immersed complete and oriented minimal surface in  $\mathbf{H}^n$  with Gaussian curvature  $K$ . Suppose  $M$  has finite topological type and*

$$-\int_M (1 + K) < +\infty,$$

*then the asymptotic boundary of  $M$  is a rectifiable 1-varifold with finite mass.*

Proof. By the hypothesis and the Gauss equation,

$$\int_M |A|^2 < \infty.$$

Therefore the corollary is followed by Theorem 2.2 and Theorem 3.2.

REMARK 3.4. 1. Let  $M$  be a properly immersed complete minimal surface in  $\mathbf{H}^n$  with minimal area growth and finite topological type. By Theorem 3.1,  $M$  is a 2-current with finite mass when  $M$  is considered as a current in  $\mathbf{R}^n$ . Then Theorem 3.2 implies readily that asymptotic boundary  $\partial M$  coincides with the boundary current of  $M$  in  $\mathbf{R}^n$ , which generalizes Proposition 6 of [1].

2: It would be an interesting question whether the following equality holds for the properly immersed complete minimal surfaces in  $\mathbf{H}^n$  with minimal area growth:

$$\sup \frac{v_H(t)}{\cosh t - 1} = \int_{\partial M} \theta d\mathcal{H}^1 \text{ (mass of } \mathcal{V}\text{)}.$$

ACKNOWLEDGEMENT This work was supported by National Science Fund of China.

---

#### References

- [1] M. T. Anderson: *Complete minimal varieties in hyperbolic space*, Invent.math. **69** (1982), 477-494.
- [2] Q. Chen: *On the total curvature and area growth of minimal surfaces in  $\mathbf{R}^n$* , Manu. Math.92 (1997), 135-142.
- [3] S. S. Chern and R. Osserman: *Complete minimal surface in  $E^N$* , J. d'Analyse Math. **19** (1967), 15-34.
- [4] M. P. do Carmo: *Differential Geometry of Curves and Surfaces*, Prentice-Hall Inc., 1976.
- [5] L. P. Jorge and W. H. Meeks: *The topology of minimal surfaces of finite total Gaussian curvature*, Topology **22** (1983), 203-221.
- [6] A. Kasue: *Gap theorems for minimal submanifolds of Euclidean space*, J.Math.Soc.Japan **38**(3) (1986), 473-492.
- [7] R. Osserman: *A survey of minimal surfaces*, Van Norstrand Rienhold, New York.
- [8] L. Simon: *Lectures on Geometric Measure Theory*, C.M.A. Australian National University Vol.3, 1983.

Q.Chen  
Department of Mathematics,  
The University of Science and Technology of China,  
Hefei, Anhui 230026,  
P. R. China

Y.Cheng  
Department of Mathematics,  
The University of Science and Technology of China,  
Hefei, Anhui 230026,  
P. R. China